DESCRIPTION

Under these items the contractor shall furnish and install a wireless, battery-powered magnetometer vehicle detection system as shown in the contract documents or where directed by the engineer.

The detection system shall provide accurate roadway information as needed to support traffic signal control. The wireless, battery-powered magnetometer vehicle detection system shall consist of one or more of the following:

- battery-powered sensors installed in-pavement in each traffic lane
- access points mounted on the side of the roadway, serving as the communications hub for the installation
- optional wireless repeaters mounted on the side of the roadway, serving to extend the radio range of an access point
- Contact Closure Interface (CCI) cards to support the interface between an access point and a standard 170/2070 controller using contact closure signals
- software to control and configure the sensors, access points, and repeaters
- software to store and retrieve detection data

Communications between the sensors and the access point or repeater and between the repeater and access point shall be via radio. Detection data shall be relayed from each access point to a local 170/2070 controller for real-time vehicle presence detection using contact closure signals. As an option, data shall be capable of being relayed from each access point to a central software system or central server over standard IP (Internet Protocol) networks.

MATERIALS

All sensor components shall be contained within a single housing. The sensor housing shall conform to NEMA Type 6P and IEC IP68 standards. All access point components shall be contained within a single housing. The access point housing shall conform to NEMA Type 4X and IEC IP67 standards. All repeater components shall be contained within a single housing. The repeater housing shall conform to NEMA Type 4X and IEC IP67 standards.

The sensor components shall be fully encapsulated within the housing to prevent moisture from degrading the components. The sensor housing shall be capable of being installed in a 4” diameter hole approximately 2 1/4” deep. An access point shall be no larger than 12” H x 8” W x
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4” D. A repeater shall be no larger than 5” H x 4” W x 4” D. An access point and a repeater shall weigh no more than 4 pounds (1.8 kg) each. An access point shall support at least 48 sensors. A repeater shall support at least 10 sensors.

The sensor, access point and the repeater shall operate at temperatures from -37 F to +176 F. A sensor shall be battery-powered with an average lifetime of ten (10) years when the sensor is configured for and operating under normal traffic conditions. A repeater shall be battery-powered and the battery shall be field replaceable. An access point shall be factory-configurable to support at least two (2) different power options:

- Power shall be supplied via an isolated nominal 48 VDC (36-58 VDC) input, consuming a maximum of 3W and providing 1500 V isolation and 5 kV surge protection
- Power shall be supplied via a non-isolated nominal 12 VDC (10-15 VDC) input, consuming a maximum of 2W

Each sensor shall detect a vehicle by magnetometer-type detection by measuring changes in the earth’s magnetic field near the sensor as caused by a stopped or passing vehicle. The sensor shall sample the earth’s magnetic field at a rate of 128 Hz and shall communicate time-stamped ON and OFF vehicle detection events. As an option, the sensor shall provide a mode where the complete X-Y-Z magnetic signatures of detected vehicles are transmitted as data. In the event of a detector lock, each sensor shall automatically recalibrate. Each sensor shall communicate by radio to a nearby access point or repeater. Each sensor shall transmit its detection data within 150 ms of a detected event. Each sensor shall automatically re-transmit a detected event if no acknowledgement is received from the access point. Each sensor may stop retransmission after 8 attempts. After losing radio contact because of stopped vehicles over or near the sensor, each sensor shall be capable of re-establishing the radio link with its supporting access point or receiver in less than 2 seconds. Each sensor shall transmit a unique identifying code and shall respond within 100 seconds when the access point is powered on. When no access point or repeater is present or powered on, the sensors shall not be required to detect vehicles.

The radio links between each sensor and access point or repeater and between each repeater and access point shall conform to the following requirements: The physical layer of the radio links between each sensor and access point or repeater and between each repeater and access point shall conform to published standards. The center frequencies, bandwidths, and transmit power levels of the radio links shall allow operation in an unlicensed frequency band. Frequency channels shall be employed by the sensors, access points, and repeaters to avoid interference with other devices operating in the unlicensed band. The frequency channels shall be user-configurable and at least 16 frequency channels shall be supported. The link budget (transmit power plus transmit antenna gain plus receive antenna gain)
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gain minus receive sensitivity, where receive sensitivity shall assume a 1% packet error rate) for all radio links shall be 93 dB or greater.

Each sensor in an installation shall be capable of being individually configured with its own sensitivity level. A single sensor shall be capable of being configured with a sensitivity level that approximates the detection zone of a standard 6' x 6' inductive loop. Each sensor shall be capable of being configured with relatively higher or lower sensitivity levels as may be required to detect bicycles or motorcycles. Up to two sensors properly configured shall be capable of detecting motorcycles in a standard traffic lane and bicycles in a designated bicycle lane.

An access point shall support the relay of sensor detection data through several interfaces as required by the application. Detection data shall be communicated to a standard roadside 170/2070 controller via CCI cards capable of being installed in standard contact closure input shelves. As an option, detection data shall be communicated over TCP/IP via an integrated 10Base-T Ethernet interface. As an option, detection data shall be communicated as IP data over GSM-based cellular data services via an integrated GPRS cellular modem. As an option, detection data shall be communicated as IP data over CDMA-based cellular data services via an integrated 1xRTT cellular modem. The access point shall be capable of simultaneously communicating detection data via the contact closure interface, optional Ethernet interface, and optional cellular data modem interface.

Each sensor, access point, and repeater shall be capable of accepting software and firmware upgrades. The wireless battery-powered magnetometer vehicle detection system shall provide software operating on conventional notebook/portable PCs to support configuration of a sensor, access point, repeater and store & retrieve detection data.

Each Contact Closure Interface (CCI) card shall provide detector data as contact closure signals to the 170/2070 controller. A CCI card shall directly plug in to standard 170/2070 input files or NEMA detector racks. One or more CCI cards shall provide up to 256 channels of detection data from a single access point’s supported sensors, where each channel comprises an optically isolated contact closure relay and, if configured for TS2 operation, an additional contact closure relay to indicate the channel status. Each CCI card shall be configurable by providing contact closure signals in either presence or pulse mode with up to 31 seconds of delay timing and 7.5 seconds of extension (carryover) timing. The CCI card front panel shall provide status LEDs to monitor detection channel status, line quality and fault monitor. The CCI card front panel shall provide switches to select and configure presence or pulse mode, delay timing and extension timing. A CCI card shall be powered by the 170/2070 controller backplane via an 11-26 VDC input. A CCI card shall be surge protected to GR-1089 standards. A CCI card shall operate at...
temperatures from -37 F to +176 F. A CCI card shall operate in humidity up to 95% (non-condensing).

Silicone sealant used to secure and cover the sensor in the cored hole in the pavement shall conform to the provisions of §705-05, Silicone Joint Sealants for Pavements.

CONSTRUCTION DETAILS

Each sensor shall be installed in the roadway at the locations shown on the contract drawings or as ordered by the engineer. The roadway shall be core drilled to provide a 4” diameter hole, 2.25” deep. A small layer of silicone sealant shall be applied to cover the bottom of the hole. The sensor shall then be placed on top of this layer in the correct orientation as clearly marked on the sensor. The sensor shall be fully encapsulated with the silicone sealant to the lip of the cored hole.

The maximum distance between a sensor installed in the roadway and an access point or a repeater with a clear line-of-sight between devices shall be at least 150’ for an access point or repeater installed 24’ above the roadway, at least 100’ for an access point or repeater installed 18’ above the roadway and at least 75’ for an access point or repeater installed 12’ above the roadway. The maximum distance between an access point and a repeater shall be at least 750’ when both units are installed 18’ above the roadway and with a clear line-of-sight between devices.

Each installation of the wireless battery-powered magnetometer vehicle detection system shall consist of one or more sensors installed in each traffic lane where presence detection is required, avoiding sources of magnetic noise such as underground power cables, overhead high tension power cables, light rail or subway tracks, and power generation stations and sub-stations. The sensors shall be located as specified by the contract drawings, with each sensor’s supporting access point or receiver installed no farther than the maximum range indicated above.

The contractor shall not damage the sensors and other equipment during construction. The sensors shall be removed and installed during various phases and sub-phases in accordance with the contract drawings. Core holes left in the pavement upon removal of sensors shall be filled with asphalt cold patch by the contractor at no additional cost to the State. The contractor shall ensure that the wireless battery-powered magnetometer vehicle detection system operates according to specification during all phases and sub-phases of construction. All equipment shall become the property of NYSDOT upon project completion.
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METHOD OF MEASUREMENT

The wireless, battery-powered magnetometer vehicle detection system will be measured as the number of units satisfactorily installed in accordance with the contract documents.

BASIS OF PAYMENT

The unit price bid for furnishing and installing each item shall include the cost of furnishing all labor, materials, equipment, tools and all necessary tests to satisfactorily complete the work in accordance with the contract documents.